

# Actuator

## ID18

ID18 is a robust and powerful actuator up to 18,000N thrust, which is designed for outdoor applications, such as solar tracker. There are several options available, including Ball screw spindle, ACME screw spindle, and different kinds of sensors for positioning feedback. The motor can be replaced directly without disassembling the actuator, which is convenient for maintenance.



### Features and Options

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**Main application:** Industry, Solar tracker

**Standard features:**

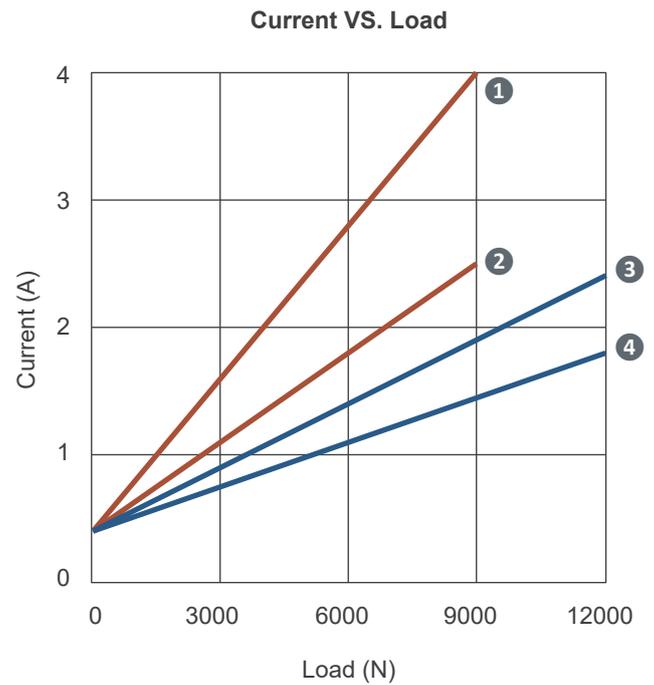
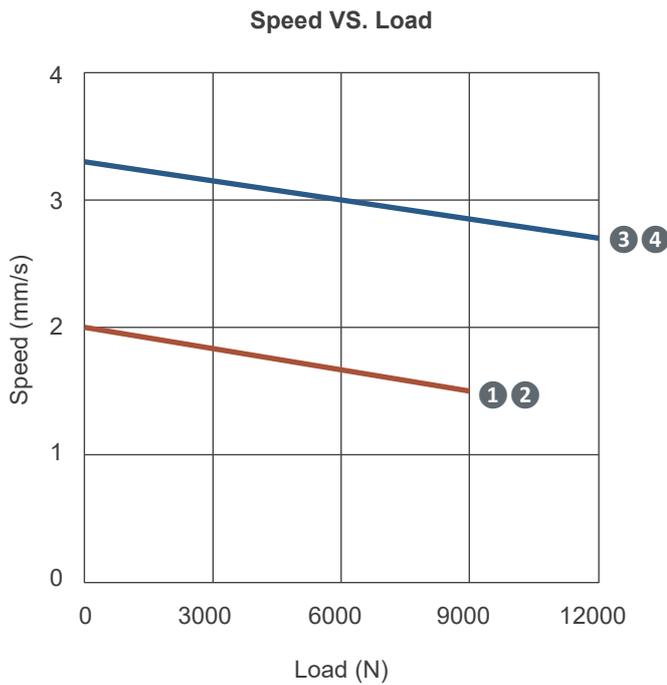
- Input voltage: 24V DC / 36V DC
- Rated load: 9,000N (ACME screw) / 12,000N (Ball screw)
- Max. static load: 36,000N
- Max. dynamic load: 12,000N (ACME screw) / 18,000N (Ball screw) in push and pull direction
- Max. speed at no load: 3.3mm/sec (Typical value)
- Stroke: 610mm (24") / 914mm (36") / 1219mm (48") (other strokes are available)
- IP level: IP65 (Static; non-action)
- Preset limit switches
- Steel extension tube
- Color: Black
- Power cord length: 250mm
- Side cable outlet
- Duty cycle: 10%, max. 2 min. continuous operation in 20 min.
- Operating ambient temperature: -25°C ~ +65°C
- Compliant with CE Marking, EMC Directive 2014/30/EU

**Options:**

- Relative positioning signal feedback with single Hall effect sensor
- Positioning signal feedback with Reed sensor
- Analog positioning feedback with Potentiometer (POT)
- Bottom cable outlet

## Performance Data

No.	Model No.	Input voltage (V)	Gear ratio	Motor code	Spindle type	Max. load (N)	Typical speed (mm/s)*		Typical current (A)*	
							No load	Full load	No load	Full load
1	ID18-2458S3A	24	58:1	S	ACME screw	9000	2.0	1.5	0.4	4.0
2	ID18-3658S3A	36	58:1	S	ACME screw	9000	2.0	1.5	0.4	2.5
3	ID18-2458S5B	24	58:1	S	Ball screw	12000	3.3	2.7	0.4	2.4
4	ID18-3658S5B	36	58:1	S	Ball screw	12000	3.3	2.7	0.4	1.8



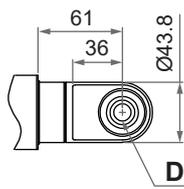
### Remarks:

- \* The typical speed or typical current means the average value neither upper limit nor lower limit. The performance curves are made with typical values.



### Front connector

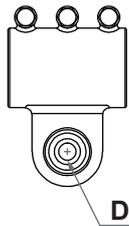
- Spherical rod eye



Diameter code	Diameter of pivot (D)
1	Ø19mm (standard)
0	Ø12.7mm

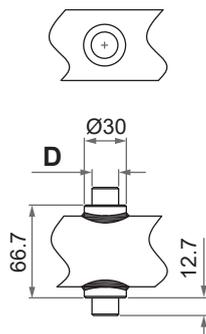
### Rear connector

- Tube clamp with spherical rod eye (standard)



Diameter code	Diameter of pivot (D)
1	Ø19mm (standard)
0	Ø12.7mm

- With trunnion mount

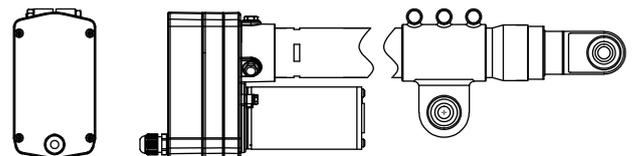
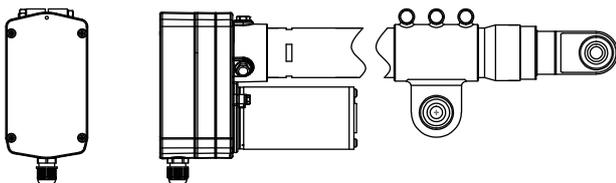


Diameter code	Diameter of pivot (D)
T	Ø19mm

### Location of cable outlet

1: Side cable outlet (standard)

0: Bottom cable outlet



## Cable with Flying Leads

- Basic (Without positioning feedback)

	Wire color	Definition	Descriptions
Power wires	Red	DC power	Connect red wire to "Vdc +" & black wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it.
	Black		

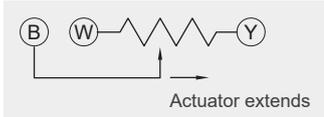
- With single Hall effect sensor positioning feedback

	Wire color	Definition	Descriptions
Power wires	Red	DC power	Connect red wire to "Vdc +" & black wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it.
	Black		
Signal wires	White	Vin	Voltage input range: 5 ~ 20V
	Yellow	Hall output	High= Input - 1.2V ( $\pm 0.6V$ ) Low= GND Hall signal data:  Resolution: Ball screw 20 PPI, ACME screw 32 PPI
	Blue	GND	

- With reed sensor positioning feedback

	Wire color	Definition	Descriptions
Power wires	Red	DC output	Connect red wire to "Vdc +" & black wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it.
	Black		
Signal wires	Yellow	Data	Resolution: Ball screw 30 PPI, ACME screw 48 PPI
	White	GND	

● With Potentiometer (POT) absolute positioning feedback

	Wire color	Definition	Descriptions																	
Power wires	Red	DC power	Connect red wire to "Vdc +" & black wire to "Vdc -" of DC power to extend the actuator. Switch the polarity of DC input to retract it.																	
	Black																			
Signal wires	Yellow	Vin	Input voltage 70V max.																	
	Blue	POT output	<p>1. Potentiometer specification:</p> <ul style="list-style-type: none"> <li>- 10K ohm, 10 turns.</li> <li>- Tolerance <math>\pm 5\%</math></li> </ul> <p>2. Output voltage: The voltage (resistance) between blue and white increases linearly from about 0 when the actuator extends, and decreases when it retracts.</p>  <p>3. There are different resolutions according to the stroke length (as table below)</p> <table border="1" data-bbox="684 831 1437 1149"> <thead> <tr> <th>Spindle type</th> <th>Stroke (mm)</th> <th>Resistance (tolerance: <math>\pm 0.3K\Omega</math>)</th> </tr> </thead> <tbody> <tr> <td rowspan="3">Ball screw</td> <td>610</td> <td>0.3 ~ 8.6</td> </tr> <tr> <td>914</td> <td>0.3 ~ 7.7</td> </tr> <tr> <td>1219</td> <td>0.3 ~ 8.4</td> </tr> <tr> <td rowspan="3">ACME screw</td> <td>610</td> <td>0.3 ~ 8.1</td> </tr> <tr> <td>914</td> <td>0.3 ~ 7.9</td> </tr> <tr> <td>1219</td> <td>0.3 ~ 8.1</td> </tr> </tbody> </table>	Spindle type	Stroke (mm)	Resistance (tolerance: $\pm 0.3K\Omega$ )	Ball screw	610	0.3 ~ 8.6	914	0.3 ~ 7.7	1219	0.3 ~ 8.4	ACME screw	610	0.3 ~ 8.1	914	0.3 ~ 7.9	1219	0.3 ~ 8.1
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	914	0.3 ~ 7.9																		
	1219	0.3 ~ 8.1																		
White	GND																			

## Ordering Key

	ID18 - 24 58 S 3A C19 - 1 1 H 1 B 5 1
<b>Input voltage</b>	24: 24V DC 36: 36V DC
<b>Gear ratio</b>	58: 58:1
<b>Motor code</b>	S: Standard motor (2300rpm)
<b>Spindle type</b>	3A: ACME screw, 3.175mm pitch 5B: Ball screw, 5.08mm pitch
<b>Stroke</b>	610: 610mm (24") 914: 914mm (36") C19: 1219mm (48")
<b>Front connector</b> (Refer to Page 4)	1: Spherical rod eye, Ø19mm (3/4") (standard) 0: Spherical rod eye, Ø12.7mm (1/2")
<b>Rear connector</b> (Refer to Page 4)	1: Tube clamp with spherical bearing, Ø19mm (3/4") (standard) 0: Tube clamp with spherical bearing, Ø12.7mm (1/2") T: With trunnion mount, Ø19mm (3/4")
<b>Positioning feedback</b>	H: Single Hall effect sensor R: Reed sensor P: Potentiometer 0: None
<b>Cable</b>	1: Bare wires / 250mm / Black
<b>Color</b>	B: Black
<b>IP level</b>	5: IP65
<b>Location of cable outlet</b> (Refer to Page 4)	1: Cable outlet at body side (standard) 0: Cable outlet at body bottom